

The paper as originally published contained the following errors which have since been corrected:

- Page 243, middle of the page: replace

$$\ell_0(b') = \nu_{\pi_0}(b') = \frac{|\Phi_b|}{K} \gamma^{\Delta(b)} L_0(b)$$

by

$$\ell_0(b') = \nu_{\pi_0}(b') = \frac{|\Phi_{b'}|}{K} \gamma^{\Delta(b')} L_0(b').$$

- Page 243, paragraph after the above equation: replace

$$\mu_0(b') = \frac{|\Phi_b|}{K} \gamma^{\Delta(b)} U_0(b) - \lambda \text{ is an upper bound.}$$

by

$$\mu_0(b') = \frac{|\Phi_{b'}|}{K} \gamma^{\Delta(b')} U_0(b') - \lambda \text{ is an upper bound.}$$

- Page 243, after the above equation: replace

$$\mu_0(b) = \max \left\{ \ell_0(b), \frac{|\Phi_b|}{K} \gamma^{\Delta(b)} U_0(b) - \lambda \right\}$$

by

$$\mu_0(b') = \max \left\{ \ell_0(b'), \frac{|\Phi_{b'}|}{K} \gamma^{\Delta(b')} U_0(b') - \lambda \right\}.$$

- Page 244, line 3 in Algorithm 4: replace

b' is blocked by any ancestor node in \mathcal{D}

by

x is blocked by any ancestor node in \mathcal{D}

- Page 247 and page 260, Lemma 4.1: replace

where $b' = \tau(b, a, z)$ is a child of b .

by

where $b' = \tau(b, a^*, z)$ is a child of b .

- Page 247 and page 260, Lemma 4.2: replace

...a belief node in an optimal regularized policy **that satisfies $U(b')$** .

by

...a belief node in an optimal regularized policy **derived from \mathcal{D}** .